

Dynamics and geometry in infinite-dimensional hyperbolic spaces

Tushar Das

Outline

Gromov hyperbolic
spaces

Classification of
isometries

Kleinian groups

Theorems on the
radial limit set

Patterson-Sullivan
theory

joint with
David Simmons (UNT)
Bernd Stratmann (Bremen)
Mariusz Urbański (UNT)

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Discrete actions of hyperbolic isometries

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The study of discrete groups acting on two- and three-dimensional Euclidean open balls by hyperbolic isometries began at the end of 19th century with the works of **Fuchs, Klein and Poincaré**.

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Greatly popularized in scientific and artistic circles via the seminal work of **Mandelbrot and Escher**.



Circle Limit I, Escher
(1958)

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...once more, with (an infinite-dimensional) feeling

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“Séminaire Sullivan”, IHÉS 1983.

Dennis Sullivan in the early '80s indicated a possibility of developing the theory of discrete groups acting by hyperbolic isometries on the open unit ball of a separable Hilbert space.

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Asymptotic invariants of infinite groups

Misha Gromov lamented the paucity of results regarding such actions and encouraged their investigation:

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Misha Gromov lamented the paucity of results regarding such actions and encouraged their investigation:

*The spaces like this ... look as **cute and sexy** to me as their finite-dimensional siblings but they have been for years **shamefully** neglected by geometers and algebraists alike.*

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$$\langle x|y \rangle_z := \frac{1}{2}[d(x, z) + d(y, z) - d(x, y)].$$

¹Denotes an additive asymptotic.

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Definition

Let (X, d) be a metric space. For three points $x, y, z \in X$, we define the **Gromov product** of x and y with respect to z by

$$\langle x|y \rangle_z := \frac{1}{2}[d(x, z) + d(y, z) - d(x, y)].$$

Definition

(X, d) is **hyperbolic** (or **Gromov hyperbolic**) if for every four points $x, y, z, w \in X$ we have

$$\langle x|z \rangle_w \gtrsim^1 \min(\langle x|y \rangle_w, \langle y|z \rangle_w).$$

We will refer to this inequality as **Gromov's inequality**.

¹Denotes an additive asymptotic.

Examples of Gromov hyperbolic spaces

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Every CAT(-1) space is Gromov hyperbolic. In particular, the following examples are Gromov hyperbolic:

- ▶ Standard hyperbolic space \mathbb{H}^n
- ▶ Complex and quaternionic hyperbolic space
- ▶ Infinite-dimensional hyperbolic space $\mathbb{H}^\infty \subseteq \ell^2$

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- ▶ A “generic” finitely presented group with its Cayley metric

Examples of Gromov hyperbolic spaces

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- ▶ Any \mathbb{R} -tree
- ▶ A “generic” finitely presented group with its Cayley metric

Definition

A Gromov hyperbolic space X is **proper** if $d(0, \cdot) : X \rightarrow \mathbb{R}$ is proper. In other words, if for all $r > 0$ the set $\overline{B}(0, r)$ is compact.

Here 0 is a distinguished point that we fix in X .

The boundary of a hyperbolic space

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Any Gromov hyperbolic space X has a **Gromov boundary** ∂X , analogous to the sphere at infinity of standard hyperbolic space. It is defined in a similar way to the completion of a metric space, with the quantity

$$e^{-\langle x|y \rangle_0}$$

playing a role analogous to the distance function.

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The most important fact about the Gromov boundary is the following heuristic:

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playing a role analogous to the distance function.

The most important fact about the Gromov boundary is the following heuristic: **The Gromov product may be extended to the boundary while preserving key formulas!**

Proposition

For each $a > 1$ sufficiently small, there exists a complete metric D_a on ∂X satisfying the following asymptotic:

$$D_a(\xi, \eta) \asymp_{\times} a^{-\langle \xi | \eta \rangle_0}. \quad (2.1)$$

If X is proper, then $(\partial X, D_a)$ is compact.

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A metric on ∂X

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D_a is a generalization of the spherical metric on the Gromov boundary of standard hyperbolic space. It is often called a *visual metric*.

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Remark

For CAT(-1) spaces, and in particular for the standard model of hyperbolic geometry, the above proposition holds for any $1 < a \leq e$. In particular, $a = e$ gives the spherical metric.

Convergence of sequences

Dynamics and
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Definition

Fix a sequence $(x_n)_n$ in X and a point $\eta \in \partial X$. We say that $(x_n)_n$ **converges to η** if

$$\langle x_n | \eta \rangle_0 \xrightarrow{n} \infty.$$

[Idea: $a^{-\langle x_n | \eta \rangle_0} \xrightarrow{n} 0$]

In this case, we write $x_n \xrightarrow{n} \eta$.

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A metric on $\partial X \setminus \{\xi\}$

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Lemma

Let $E_\xi := \partial X \setminus \{\xi\}$ for some fixed $\xi \in \partial X$. If $x_n \rightarrow \xi$, then

$$e^{d(0, x_n)} D_{x_n}(\eta_1, \eta_2) \xrightarrow{n, \times} e^{-[\langle \eta_1 | \eta_2 \rangle_0 - \sum_{i=1}^2 \langle \eta_i | \xi \rangle_0]}.$$

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Here $a_n \xrightarrow[n, \times]{} b$ means $\frac{1}{K} \leq \frac{\liminf a_n}{b} \leq \frac{\limsup a_n}{b} \leq K$.

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Corollary

There exists a metric

$$D_{\xi, 0}(\eta_1, \eta_2) \asymp_{\times} e^{-[\langle \eta_1 | \eta_2 \rangle_0 - \sum_{i=1}^2 \langle \eta_i | \xi \rangle_0]}.$$

Note that in CAT(-1) you have a limit and equality respectively.

Classification of isometries

Theorem

Let g be an isometry preserving some $\xi \in \partial X$. Then $\exists t \in \mathbb{R}$ such that

A $B_\xi(x, g^n x) \asymp_+ nt$

B $D_{\xi,0}(g^n(\eta_1), g^n(\eta_2)) \asymp_\times e^{nt} D_{\xi,0}(\eta_1, \eta_2)$

We call e^{-t} the *dynamical derivative* of g at ξ .

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Here $B_\xi(x, y) := \liminf_{z \rightarrow \xi} [d(z, x) - d(z, y)]$ is the Busemann function. In Hilbert space, it describes the signed horospherical distance between horospheres centered at ξ through x and y respectively.

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Definition

Let g be an isometry preserving some $\xi \in \partial X$.

- a ξ is called **indifferent** fixed point if $t = 0$
- b ξ is called **attracting** fixed point if $t > 0$
- c ξ is called **repelling** fixed point if $t < 0$

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Definition

A group of isometries G is

- a **elliptic** if the orbit of some base point is bounded.
- b **parabolic** if there exists a ξ that is an indifferent fixed point for every element of the group and G is not elliptic.
- c **hyperbolic** if there exists some attracting or repelling fixed point for the group.

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Every group is exactly one of the 3 types above.

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- One can therefore classify isometries according to their cyclic group.

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Theorem

Every group is exactly one of the 3 types above.

Remark

- One can therefore classify isometries according to their cyclic group.
- Note that this proves the existence of fixed points for isometries with unbounded orbits.

Example

There are examples of parabolic isometries whose orbits accumulate at their fixed point on the boundary but recur infinitely often to some bounded region in the interior.

The earliest examples we could find were discovered in a different context by Edelstein in the '60s.

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Definition

Let G be a group of isometries acting on a hyperbolic space X . We say that G is **strongly discrete** if for every $r > 0$

$$\#\{g \in G : g(0) \in B(0, r)\} < \infty.$$

We say that a group is **Kleinian** if it is strongly discrete.

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A Kleinian group G is **non-elementary** if there is no finite set $F \subseteq \partial X$ or bounded set $F \subseteq X$ such that $G(F) = F$.

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Observation

If X is proper, then strong discreteness is equivalent to a variety of notions of discreteness; however this is not true in general.

Definition

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Observation

If X is proper, then strong discreteness is equivalent to a variety of notions of discreteness; however this is not true in general. The simplest counterexample, say in Hilbert space, is an infinite-rank parabolic group.

Radial convergence

Observation

Fix a sequence $(x_n)_n$ in X and a point $\eta \in \partial X$. Suppose that $d(0, x_n) \xrightarrow[n]{\rightarrow} \infty$, and that either of the following equivalent asymptotics holds:

$$\langle 0 | \eta \rangle_{x_n} \asymp 0$$

$$\langle x_n | \eta \rangle_0 \asymp d(0, x_n).$$

Then $x_n \xrightarrow[n]{\rightarrow} \eta$.

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$$\langle x_n | \eta \rangle_0 \asymp d(0, x_n).$$

Then $x_n \xrightarrow{n} \eta$.

Definition

In the situation above, we say $(x_n)_n$ **converges radially to η** .

We say that $(x_n)_n$ **converges uniformly radially to η** if it converges radially and if the distances $(d(x_n, x_{n+1}))_n$ remain bounded.

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Equivalent definition of radial convergence

As in the case of standard hyperbolic space, radial convergence can also be defined in terms of shadows; however we must generalize what we mean by “shadow”:

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Equivalent definition of radial convergence

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Definition

For each $\sigma > 0$ and $x \in X$, let

$$\text{Shad}(x, \sigma) = \{\eta \in \partial X : \langle 0|\eta \rangle_x \leq \sigma\}.$$

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Observation

Suppose that $d(0, x_n) \xrightarrow{n} \infty$. Then $x_n \xrightarrow{n} \eta$ radially if and only if there exists $\sigma > 0$ such that for all $n \in \mathbb{N}$,

$$\eta \in \text{Shad}(x_n, \sigma).$$

Limit sets of a Kleinian group

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Definition

Let G be a Kleinian group. The sets

$$L(G) := \{\eta \in \partial X : \exists g_n(0) \xrightarrow{n} \eta\}$$

$$L_r(G) := \{\eta \in \partial X : \exists g_n(0) \xrightarrow{n} \eta \text{ radially}\}$$

$$L_{ur}(G) := \{\eta \in \partial X : \exists g_n(0) \xrightarrow{n} \eta \text{ uniformly radially}\}$$

denote the **limit set**, **radial limit set**, and **uniformly radial limit set**, respectively.

The theorem of Bishop and Jones

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For each $s > 0$, we define the **Poincaré series** for G with exponent s to be the series

$$\Sigma_s(G) := \sum_{g \in G} a^{-sd(0, g(0))}.$$

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We define the **critical exponent** of G to be the number

$$\delta(G) := \inf\{s > 0 : \Sigma_s(G) < \infty\}.$$

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$$\delta(G) := \inf\{s > 0 : \Sigma_s(G) < \infty\}.$$

Definition

A measure μ is **Ahlfors s -regular** if

$$\mu(B(x, r)) \asymp_{\times} r^s.$$

Theorem

Let G be a non-elementary Kleinian group. For every $s < \delta$, there exists μ supported on $L_{ur}(G)$ such that μ is Ahlfors s -regular.

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Theorem

Let G be a non-elementary Kleinian group. For every $s < \delta$, there exists μ supported on $L_{ur}(G)$ such that μ is Ahlfors s -regular.

Corollary

For any nonelementary Kleinian group G ,

$$\text{HD}(L_r(G)) = \text{HD}(L_{ur}(G)) = \delta(G).$$

Theorem

Let G be a non-elementary Kleinian group. For every $s < \delta$, there exists μ supported on $L_{ur}(G)$ such that μ is Ahlfors s -regular.

Corollary

For any nonelementary Kleinian group G ,

$$\text{HD}(L_r(G)) = \text{HD}(L_{ur}(G)) = \delta(G).$$

Bishop and Jones (Acta '97) proved this theorem in the case where X is a finite-dimensional hyperbolic space.

A group for which $\delta \neq \text{HD}(L_{\text{ur}})$

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Example

There exists a group G with:

- a $\text{HD}(L_{\text{r}}(G)) < \infty$
- b $\delta = \infty$
- c G is “parametrically discrete”
- d G acts irreducibly on \mathbb{H}^∞

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- d G acts irreducibly on \mathbb{H}^∞

Idea.

Start with a Schottky group H generated by two elements that are both “rotations” - i.e. cycle through all the coordinates, and let $G := \{g : g(H(0)) = H(0)\}$. Then $L(G) = L(H)$ but $\#\text{Stab}_0(G) = \infty$ and so G is not strongly discrete. □

Quasiconformal measures

Definition

Fix $s > 0$. A measure μ on ∂X is said to be **s -quasiconformal** with respect to G if for every Borel set $A \subseteq \partial X$ and for every $g \in G$, we have

$$\mu(g(A)) \asymp_{\times} \int_A a^{sB_{\eta}(0, g^{-1}(0))} d\mu(\eta).$$

Here $B_{\eta}(0, g^{-1}(0)) := \langle g^{-1}(0) | \eta \rangle_0 - \langle 0 | \eta \rangle_{g^{-1}(0)}$.

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- ▶ Interpret the expression

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- ▶ Interpret the expression

$$a^{B_{\eta}(0, g^{-1}(0))}$$

as being “the derivative of g at η ”.

- ▶ If X is a CAT(-1) space, then this interpretation can be made explicit, i.e.

$$a^{B_{\eta}(0, g^{-1}(0))} = \lim_{\xi \rightarrow \eta} \frac{d(g\xi, g\eta)}{d(\xi, \eta)}.$$

Existence and uniqueness of δ -quasiconformal measures

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Definition

A Kleinian group G is **of divergence type** if its Poincaré series diverges at its critical exponent, i.e. if

$$\Sigma_\delta(G) = \infty.$$

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If G is a nonelementary Kleinian group of divergence type, then there exists a δ -quasiconformal measure μ supported on the radial limit set $L_r \subset \partial X$.

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If X is a CAT(-1) space, then μ can be made conformal, and is unique up to a constant.

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Theorem

Given a non-elementary Kleinian group G and a conformal measure μ ,

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Ahlfors provides Thurston's proof of this theorem in the case that X is standard hyperbolic space and G is of the first kind, i.e.

$$L(G) = \partial X = S^{\dim X - 1} \text{ and } \delta = \dim X - 1.$$

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- ▶ Standard Patterson-Sullivan theory constructs conformal μ on ∂ ČechStone(\overline{X})
- ▶ By Ahlfors-Thurston we get that μ is supported on L_r
- ▶ Show that $L_r \subset \partial X$

A group without a conformal measure!

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Example

There exists an infinitely generated Schottky group of convergence type with no conformal measure.

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A group without a conformal measure!

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There exists an infinitely generated Schottky group of convergence type with no conformal measure.

Idea.

G is constructed so that there exists a $B(0, R)$ such that any two geodesics between any two of the generating balls intersects $B(0, R)$. This gives us that $L_r(G) = L(G)$.

Heuristically, the diameters of the generating balls must converge to zero at a specific rate that forces the group to be of convergence type. Then Ahlfors–Thurston implies that there is no conformal measure. □

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Start with a *Borel* conjugacy T between two actions of non-elementary strongly discrete groups Γ_1 and Γ_2 .

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If the Poincaré series for Γ_1 diverges at δ , then

T agrees (μ_1 -a.e.) with a *conformal* conjugacy between Γ_1 and Γ_2 .

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Note that if we assume T to be Lipschitz, then it suffices to assume that Γ_1 is of divergence type and that μ_1 is δ -quasiconformal. In such a case μ_2 will turn out to be δ -quasiconformal as well.

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Note that if we assume T to be Lipschitz, then it suffices to assume that Γ_1 is of divergence type and that μ_1 is δ -quasiconformal. In such a case μ_2 will turn out to be δ -quasiconformal as well. We are currently investigating various ramifications for groups of convergence type and Hopf's dichotomy in our setting.

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Making use of conformal measures and a Sullivan's Shadowing Lemma type argument, we prove the following

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Making use of conformal measures and a Sullivan's Shadowing Lemma type argument, we prove the following

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If G is a convex co-bounded group that is strongly discrete, then it is finitely generated and of compact type.

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If G is a convex co-bounded group that is strongly discrete, then it is finitely generated and of compact type. In particular the δ_G -dimensional Hausdorff and packing measures on $L(G)$ are finite and positive. They coincide, up to a multiplicative constant, with the δ_G -conformal measure, which is Ahlfors regular.

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Remark

This theorem may be proved without resorting to the **thermodynamic formalism** à la Bowen-Ruelle-Sinai.

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This theorem may be proved without resorting to the **thermodynamic formalism** à la Bowen-Ruelle-Sinai.

However, access to similar geometric results as well as strong stochastic properties for systems associated to large classes of **infinitely-generated** Schottky groups are via extensions of the thermodynamic formalism to such settings and *fine inducing* on (Lai-San) Young towers.

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Thank **you** for your indulgence

... on this late Saturday afternoon!

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Thank **you** for your indulgence

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and especially to **Idris**

for this wonderfully well thought out workshop.

Encore!

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Groups of compact type

Definition

A properly discontinuous group G is said to be of **compact type** when $L(G)$ is compact.

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For a properly discontinuous group G , the following are equivalent:

1. G is of compact type.
2. Every infinite subset of $G(0)$ contains an accumulation point.
3. Each sequence $(g_n(0))_{n \in \mathbb{N}}$ such that $\lim_{n \rightarrow \infty} \|g_n(0)\| = 1$ has a converging subsequence, which necessarily accumulates at an element in $L(G)$.
4. Every infinite subset of $G(0)$ contains a sequence $(z_n)_n$ such that $\langle z_n, z_m \rangle_0 \rightarrow \infty$ as $n, m \rightarrow \infty$.

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4. Every infinite subset of $G(0)$ contains a sequence $(z_n)_n$ such that $\langle z_n, z_m \rangle_0 \rightarrow \infty$ as $n, m \rightarrow \infty$.

In CAT(-1) spaces, any group of compact type acting properly discontinuously is strongly discrete.

Convex-cobounded groups

Say we're in a geodesic Gromov-hyperbolic space. For $w, z \in \overline{X}$, let $\gamma_{w,z}$ be the unique geodesic joining w and z .

$$C_\Delta(G) := \bigcup_{\xi_1, \xi_2 \in L(G)} \gamma_{\xi_1, \xi_2}^\circ.$$

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Then notice that $C_\Delta(G)$ is G -invariant, i.e. for any $g \in G$,

$$g(C_\Delta(G)) = C_\Delta(G).$$

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Definition

A properly discontinuous group G is **convex cobounded** if there exists a ball about the origin $B(0, r)$ such that $q[B(0, r) \cap C_\Delta(G)] = q[C_\Delta(G)]$.

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Theorem

Let G be properly discontinuous and of compact type.

TFAE:

1. $L_r(G) = L(G)$.
2. $L_{ur}(G) = L(G)$.
3. The group is convex-cobounded.

A “remarkable” description of $L(G)$.

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Definition

A group G is called **elementary** whenever $\#L(G) \in \{0, 1, 2\}$.

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Definition

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Theorem (It's elementary dear . . .)

For every G the following are equivalent:

1. $\#[L(G)] < \infty$.
2. Either
 - ▶ $G = \langle e \rangle$.
 - ▶ $\exists! \xi \in \partial \mathbb{B}_\infty$ parabolic with $G(\xi) = \xi$ and G consists entirely of parabolics.
 - ▶ $G = \langle g \rangle$, with g hyperbolic.
3. $\nexists g, h \in G$ hyperbolic with $Fix(g) \cap Fix(h) = \emptyset$.

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3. $\nexists g, h \in G$ hyperbolic with $Fix(g) \cap Fix(h) = \emptyset$.

Theorem (Minimality)

For every non-elementary group G , $L(G)$ is the smallest closed G -invariant subset of $\partial \mathbb{B}_\infty$ that contains at least 2 points.

Hilbert version

If you prefer to be concrete, consider real separable Hilbert space, $\mathcal{H} \equiv \ell_2$ with the standard orthonormal basis denoted by $(e_n)_n$.

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Hilbert version

If you prefer to be concrete, consider real separable Hilbert space, $\mathcal{H} \equiv \ell_2$ with the standard orthonormal basis denoted by $(e_n)_n$. Of the many models of hyperbolic space, let's focus on the **Poincaré ball** \mathbb{B}_∞ and the **Upper-half space** \mathbb{H}_∞ .

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- ▶ Just as in finite dimensions, we have the following formulae for the associated length elements:

$$ds_{\mathbb{B}}^2 := \frac{4\|dx\|^2}{(1 - \|x\|^2)^2} \quad \text{and} \quad ds_{\mathbb{H}}^2 := \frac{\|dx\|^2}{x_0^2}.$$

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Definition

Let $f : M \rightarrow N$ be a diffeomorphism. Then f is called **conformal** when there exists a differentiable positive function $\alpha : M \rightarrow \mathbb{R}$ such that for all $x \in M$ and for all $v, w \in T_x M$

$$\langle d_x f(v), d_x f(w) \rangle_{f(x)} = \alpha^2(x) \langle v, w \rangle_x .$$

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For each x , we call the number $\alpha(x)$ the *scaling constant* of the map $d_x f$.

Note that $\alpha(x)$ is equal to the operator norm $\|d_x f\|$.

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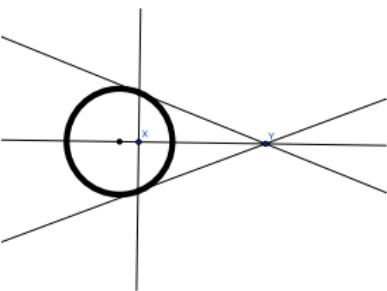
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Definition

Let $x \in \mathcal{H}$ and $\alpha > 0$. Then the **inversion** with respect to the sphere $S(x, \alpha)$ is the map

$$i_{x,\alpha} : z \mapsto \alpha^2 \frac{z-x}{\|z-x\|^2} + x$$



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Theorem (Liouville, 1850)

Let $U \in \mathcal{H}$ be a non-empty domain,
 $\phi : U \rightarrow \mathcal{H}$ be a conformal map.
Then either there exists a unique
quadruple (λ, x, y, M) with $\lambda > 0$;
 $x, y \in \mathcal{H}$ and $M \in \mathcal{O}(\mathcal{H})$ such that

$$\phi(z) = \lambda M(i_x(z)) + y,$$

or ϕ is of the form $\phi(z) = \lambda M(z) + y$.
As in the finite dimensional case, the map ϕ is
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Joseph Liouville
(1809 – 1882)

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Theorem: The conformal map $i_{-e_0, \sqrt{2}} : \widehat{\mathcal{H}} \rightarrow \widehat{\mathcal{H}}$
is a homeomorphism between $\overline{\mathbb{H}}_\infty$ and $\overline{\mathbb{B}}_\infty$ and
an isometry between \mathbb{H}_∞ and \mathbb{B}_∞ .

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Theorem (Hyperbolic isometry inside, conformal upto the boundary)

Let \mathbb{K}_∞ be either \mathbb{B}_∞ or \mathbb{H}_∞ . Then TFAE:

- (1) g is the restriction of a conformal map $\hat{g} : \hat{\mathcal{H}} \rightarrow \hat{\mathcal{H}}$ which preserves \mathbb{K}_∞ .
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- (3) g is an element of $\mathcal{M}_{\mathbb{K}}$.
- (4) g preserves the infinitesimal metric, i.e.
$$\|g_*[u]\|_{g(x), \mathbb{K}} = \|u\|_{x, \mathbb{K}} \text{ for every } x \in \mathbb{K}_\infty \text{ and all } u \in T_x \mathbb{K}_\infty.$$
- (5) g preserves the distance function $d_{\mathbb{K}}$, i.e.
$$d_{\mathbb{K}}(gx, gy) = d_{\mathbb{K}}(x, y) \text{ for every } x, y \in \mathbb{K}_\infty.$$

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Notice that

- (1) \Leftrightarrow (3) says $\mathcal{M}_{\mathbb{B}}$ is the group of conformal maps that preserve the unit ball.

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Notice that

- ▶ (1) \Leftrightarrow (3) says $\mathcal{M}_{\mathbb{B}}$ is the group of conformal maps that preserve the unit ball.
- ▶ (1) \Leftrightarrow (2) follows from **Liouville's Theorem**.

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Let us define the **Möbius group** as follows:

$$\mathcal{M}_{\mathbb{K}} := \{g : \mathbb{K}_{\infty} \rightarrow \mathbb{K}_{\infty} \mid g \text{ preserves } \langle \cdot, \cdot \rangle_{\mathbb{K}}\}$$

and let

$$\mathcal{M}_{\mathbb{K}}^* := \{g \in \mathcal{M}_{\mathbb{K}} \mid g \text{ composed of finitely many inversions}\}.$$

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Theorem (Classification of isometries of hyperbolic space)

Any isometry of hyperbolic space is conjugate to exactly one of the following:

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- (2) *Parabolic case: A bijective affine isometry on \mathbb{H}_∞ with no fixed points in the interior.*
- (3) *Hyperbolic case: A map of the form $g = \lambda M : \mathbb{H}_\infty \rightarrow \mathbb{H}_\infty$, where $0 < \lambda < 1$ and M is a bijective linear isometry on \mathbb{H}_∞ .*

Can one make sense of *orientation preserving* transformations in infinite dimensions?

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If one wanted to define orientation-preserving via the kernel of a continuous homomorphism $\mathcal{O} : \mathcal{O}(\mathcal{H}) \rightarrow \mathbb{Z}_2$ one would easily fall into a trap . . . For example, any reflection in a hyperplane on $\ell_2(\mathbb{Z})$ would be orientation-preserving.

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Example

For example, for $v, w \in \mathcal{H}$, let $H_{v,w} := \{x + w \mid x \in v^\perp\}$ be the hyperplane determined by v and w and let $r_{v,w}$ be reflection in this hyperplane given by

$z \mapsto (\text{id} - 2P_v)(z - w) + w$, where P_v is the projection onto the hyperplane v^\perp . Then $\mathcal{O}(r_{v,w})$ can be shown to equal 1, i.e. be orientation-preserving.